

sucnf.tar
; Between square brackets [...] optional fields

IOREM=NO ; [I/O Remote Module]
; [YES=Present NO=Not Present]

NB_AX=1,0,0 ; Number of Axes Boards:
; Analog [,Digital, Single Axis Analog Board]
; (from 0 to 4) [, (0,1,2) , (1=Present,0=Not Present)]

>NB_IO=2,0 ; Number of I/O Boards
; Local [,Remote]
; (from 0 to 5) [, (from 0 to 4)]

NB_AD=2 ; Number of I/O Boards with AD Converter
; (from 0 to 5)

N_T=4,0 ; Number of Output Words (T)
; Local [,Remote]

Modify Insert Erase Buffer Write Read S_find Again U_num. X_chg. J_jump. Quit

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N_T=4,0 ; Number of Output Words (T)
; Local [,Remote]

N_R=14,0 ; Number of Input Words (R)
; Local [,Remote]

IKR=NO ; [IKR Module]
; [YES=Present NO=Not Present]

TAU=0.008 ; CNC time base in sec.
; changing this value, check for TAUPLC= right value.

TAUPLC=2 ; PLC time base expressed in numbers of "TAU".
; i.e: TAU=0.008 TAUPLC=2 (PLC timing= 16ms)
; TAU=0.006 TAUPLC=3 (PLC timing= 18ms)

ALR_AXDG=ON ; (ON = Alarm enabled in case of IDD Digital
; Axes configured but not present or not powered)

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```
ALR_AXDG=ON      ; (ON  = Alarm enabled in case of IDD Digital
                  ; Axes configured but not present or not powered)
                  ; (OFF = Alarm disabled the IDD management is done
                  ;       dynamically)
```

```
;Axes Configuration
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```
N_AX=3           ; Total Number of Axes (from 0 to 12)
```

```
AX00=RFR(AN,0,0) TRN(AN,0,0)
```

```
>AX01=RFR(AN,0,1) TRN(AN,0,1)
```

```
AX02=RFR(AN,0,2) TRN(AN,0,2)
```

```
;AX03=FALSE
```

```
;AX04=FALSE
```

```
;AX05=FALSE
```

```
;Hand Wheels Configurations (those connected to encoder channels)
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```
;VL0=TRN(AN,1,0)
```

```
;VL1=TRN(AN,1,1)
```

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;Hand Wheels Configurations (those connected to encoder channels)

;VL0=TRN(AN,1,0)

;VL1=TRN(AN,1,1)

;Analog D/A Outputs Configuration

;DA00=RFR(AN,0,3)

;DA01=RFR(AN,1,3)

;DA02=RFR(AN,2,3)

Modify Insert Erase Buffer Write Read S_find Again U_num. X_chg. J_jump. Quit